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High-precision numerical estimates of Mellin-Barnes integrals based on the stationary phase contour



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Outline

- Motivation
- Overview of theoretical framework: contours
- Numerical estimation of accuracy
- \Box From Q_0^2 to Q^2
- Conclusions

A list of physical task in high-energy physics solved using the Mellin-Barnes (MB) integrals – a family of integrals in the complex plane whose integrand is given by the ratio of products of Gamma functions (two-loop massive Bhabha scattering in QED, three-loop massless form factors, static potentials, massive two-loop QCD form factors, B-physics studies hadronic top-quark physics and muon magnetic moment anomaly from lepton vacuum polarization) can be supplemented by finding the structure functions, the fragmentation functions and parton distributions in QCD analysis of the deep inelastic scattering (DIS) data. The volume of experimental data which is included in the analysis quickly increases and their accuracy improves. Numerical processing of this experimental material requires the effective methods.

Recently, significant progress has been made in the numerical computation of the MB integrals, as example, the paper by Gluza, Jelinsky,Kosower[PRD 95 (2017)]. The choice of the integration contour is of great practical importance. The best efficiency in a numerical integration of the MB integrals can be achieved on the contour of the stationary phase where the oscillations of the integrand are minimal. However, the solution of the differential equation for the stationary phase contour and its subsequent application to calculate the MB integral requires big computing expenses. Instead, it is proposed to build such approximations of the stationary phase contour that would allow the effective application of the quadrature integration formulas.

Overview of theoretical framework: contours

The inverse Mellin transform method is widely used in calculations related to DIS [M. Gluck, E. Reya PRD 14 (1976)]. The general expression for the inverse Mellin transform is written as a contour integral in the complex z-plane

$$f(x,Q^{2}) = \frac{1}{2\pi i} \int_{C} dz \ x^{-z} \tilde{f}(z,Q^{2})$$
(1)

The moments of the structure function at some fixed momentum transfer Q^2 is usually expressed in terms of the ration of Gamma function. Then Eq. (1) is a typical MB integral.

In typical DIS-data processing the integral has to be calculated more than a few millions times. Therefore, optimal numerical integration depends on the number of terms in the quadrature formula. Im z

Usually, the contour C in (1) is chosen parallel to the imaginary axis (C_0) to the right of the rightmost ^fpole in the integrand, or a straight line at an angle (C_1).

[M. Gluck, E. Reya and A. Vogt, Z. Phys. 48, 471 (1990); A. Vogt, Com. Phys. Commun. 170, 65 (2005)]

The efficient contour based on the saddle-point method of the integrand in (1) was suggested by Kosower [D.A. Kosower, Nucl. Phys. B 506, 439 (1997)]. This contour running through a saddle point of the integrand (1) in the complex z-plane has the parabolic shape.



Standard contours

We present a new approximation for the efficient contour, which close to the exact contour of the stationary phase [A. Sidorov, V. Lashkevich, OS, Phys. Rev. D97 (2018) 076009].

We will consider efficient numerical evaluation of the MB integrals for the structure functions, for two exactly solvably examples, and some MB integrals arising in the Feynman diagrams.

We will answer a question that is important from the practical point of view: how many polynoms in the quadratur formula for r.h.s. in (1) has to be used for evaluate the integral with a fixed relative error of ~ 10⁻⁴ or 10⁻¹² by using the efficient contours C_{as} and C_{K} .

Notation C_{st} - the exact stationary phase contour C_{as} - our contour [the asymptotic stationary phase contour] C_{K} - the Kosower contour

<u>Note</u>

The Mellin-Barnes integral widely used in calculations of Feynman diagrams, as massive propagator can be written as

$$\frac{1}{(p^2 - m^2)^a} = \frac{1}{\Gamma(a)} \frac{1}{2\pi i} \int_{-i\infty}^{+i\infty} dz \Gamma(a + z) \Gamma(-z) \frac{(-m^2)^z}{(p^2)^{a+z}}$$

Input: DIS



The parameterization of the F_3 structure function is typical and widely used in DIS for quarks and gluons densities

$$xF_{3}(x,Q_{0}^{2}) = Ax^{\alpha}(1-x)^{\beta}(1+\gamma x)$$
$$M_{n}(Q_{0}^{2}) = \int_{0}^{1} x^{n-1}F(x,Q_{0}^{2})dx$$
$$M(z,Q_{0}^{2}) = A\Gamma(\beta+1) \left[\frac{\Gamma(\alpha+z)}{\Gamma(\alpha+\beta+1+z)} + \gamma \frac{\Gamma(\alpha+1+z)}{\Gamma(\alpha+\beta+2+z)}\right]$$

<u>Note</u>

Earlier from QCD analysis of DIS data we extracted values of the form for NS structure functions at some fixed Q [A. Sidorov, OS, Mod. Phys. Lett. A 29 (2014)]. The Q² evolution of the structure-function non-singlet (NS) moments has a simple form and, in the leading order, is fully determined by the strong-interaction constant and by the values of the nonsinglet anomalous dimensions $\gamma_{NS}^{(0)}(n)$.

$$M_{n}(Q^{2}) = \left[\frac{\alpha_{s}(Q_{0}^{2})}{\alpha_{s}(Q^{2})}\right]^{\frac{\gamma_{NS}^{(0)}(n)}{2\beta_{0}}} M_{n}(Q_{0}^{2})$$
$$(\beta_{0} = 11 - 2n_{f}/3)$$

Restoration of structure function

The inverse Mellin transformation (1) for the xF_3

$$xF_3(x,Q^2) = \frac{1}{2\pi i} \int_{C} dz \ x^{-z} M_3(z,Q^2)$$
(1a)

$$M_{3}(z,Q_{0}^{2}) = \int_{0}^{1} dx \ x^{z-1} x F_{3}(x,Q_{0}^{2}) = A \ \Gamma(\beta+1) \left[\frac{\Gamma(\alpha+z)}{\Gamma(\alpha+\beta+1+z)} + \gamma \frac{\Gamma(\alpha+1+z)}{\Gamma(\alpha+\beta+2+z)} \right]$$

$$xF_{3}(x,Q_{0}^{2}) = A x^{\alpha} (1-x)^{\beta} (1+\gamma x)$$

$$G(z,\alpha,\beta)$$

We will calculate (1a) numerically and compare the result with exact value.

The equation for the stationary phase contour C_{st}

$$\frac{d\mathbf{x}}{d\mathbf{y}} = \frac{\operatorname{Re}\left\{\partial_{z}\ln\left[e^{-z\ln x}G(z,\alpha,\beta)\right]\right\}^{*}}{\operatorname{Im}\left\{\partial_{z}\ln\left[e^{-z\ln x}G(z,\alpha,\beta)\right]\right\}^{*}} \quad \text{with condition } \mathbf{x}(0) = c_{0},$$
$$z = \mathbf{x} + \mathbf{i}\mathbf{y}$$







Non-singlet combination of polarized quark densities

$$x\Delta q_{3}(x,Q_{0}^{2}) = Ax^{\alpha}(1-x)^{\beta}(1+\gamma x)$$
$$x\Delta q_{3}(x,Q^{2}) =$$
$$= [x\Delta u(x,Q^{2}) - x\Delta u(x,Q^{2})] - [x\Delta d(x,Q^{2}) - x\Delta d(x,Q^{2})]$$

Semi-inclusive lepton-nucleon process (SIDIS) $\ell + p \rightarrow \ell' + h + X$

$$zD_i^{\pi^+}(z) = \frac{N_0 z^{\alpha} (1-z)^{\beta} [1+\gamma(1-z)^{\delta}]}{B[\alpha+1,\beta+1]+\gamma B[1+\alpha,\beta+\delta+1]}$$

B(a,b) - the Beta function

parameters from D.de Florianet *et.al.*, PRD 95 (2017)

$$\alpha_{\rm PT}^{LO}(Q^2) = \frac{4\pi}{\beta_0} \frac{1}{\ln(Q^2/\Lambda^2)}$$

 $\alpha^{\scriptscriptstyle LO}_{\scriptscriptstyle APT}$

$$(Q^2) = \frac{4\pi}{\beta_0} \left[\frac{1}{\ln(Q^2/\Lambda^2)} + \frac{1}{1 - Q^2/\Lambda^2} \right]$$

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Polarazed nonsinglet $\Delta q_3(x)$ and nonsinglet fragmentation function $D_{u_v}^{\pi^+}(z)$ in the analytic approach to QCD

Theoretical framework: Analytic approach (APT

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APT = PT + RG + Q² - analyticity

Well-known features of APT:

D.V. Shirkov, I.L.Solovtsov, Phys. Rev. Lett. 79 (1997) 1209

analytic coupling

 $\mathcal{A}(Q^{2}) \equiv \alpha_{APT}(Q^{2}) = \frac{1}{\pi} \int_{0}^{+\infty} \frac{\rho(\sigma) d\sigma}{\sigma + Q^{2}} \quad (Kallen - Lehman \ representation)$ free from unphysical singularities $[\alpha_{PT}(Q^{2})]^{n} \Longrightarrow \mathcal{A}_{n}(Q^{2}) = \frac{1}{\pi} \int_{0}^{+\infty} \frac{\rho_{n}(\sigma) d\sigma}{\sigma + Q^{2}}$

 free from unphysical singularities and without additional parameters

infrared stable point which is independent of the scale parameter A_{OCD}

APT -> PT at large Q²

<u>Generalization: non-integer (fractional) power</u> <u>Fractional APT (FAPT)</u>

$$\left[\alpha_{PT}(Q^2)\right]^{\nu} \Longrightarrow \mathcal{A}_{\nu}(Q^2) = \frac{1}{\pi} \int_{0}^{+\infty} \frac{\rho_{\nu}(\sigma) d\sigma}{\sigma + Q^2} ,$$
$$\rho_{\nu}(\sigma) = \operatorname{Im}\left(\left[\alpha_{PT}(-\sigma)\right]^{\nu}\right)$$

A.P. Bakulev, S.V. Mikhailov, N. Stefanis, Phys. Rev. D 72 (2005) 074014 (2005); 75 (2007) 056005 A.P. Bakulev, Phys. Part. Nucl. 40 (2009) 715-756.

 $\rho_n(\sigma) = \operatorname{Im}\left(\left[\alpha_{pr}(-\sigma - i\varepsilon)\right]^n\right)$

 $\alpha_{APT}(0) = 1/\beta_0$

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FAPT: Q² - evolution SF

Kosower contour

<u>1st step</u>

$$f(x,Q^2) = \frac{1}{\pi} \int_{C'} \mathbf{Re} \Big[-idz \ F(z,Q^2) \Big],$$
$$F(z,Q^2) \equiv x^{-z} \tilde{f}(z,Q^2)$$

The saddle point: $F'(c_0, Q^2) = 0$

 $z(t) = \mathbf{x}(t) + i\mathbf{y}(t)$ with the conditions $\mathbf{x}(t_0 = 0) = c_0, \mathbf{y}(t_0) = 0$ [(x, y) - real].

(the dependence on values of the Bjorken -x and Q^2 is omitted)

[D.A. Kosower, Nucl. Phys (1997)]

$$F(z(t)) = F(c_0) - \frac{F''(c_0)}{2}t^2 + \frac{1}{6} \left[-iF^{(3)}(c_0) + 3iF''(c_0)x''(0) \right] t^3 + \dots$$

Im F(z(t)) = 0 to order $O(t^3)$:

$$z(t) = c_0 + it + \frac{F^{(3)}(c_0)}{6F''(c_0)}t^2 = c_0 + it + \frac{c_3}{2}t^2 \qquad [C_K^{(3)} - \text{contour or } C_K]$$

$$f(x,Q^{2}) = \frac{1}{\pi} \int_{0}^{\infty} \operatorname{Re}\left[\left(1 - ic_{3}t\right)F(z(t),Q^{2})\right]dt.$$

$$z(t) = c_0 + it + \frac{c_3}{2}t^2 + c_6t^4 \quad [C_K^{(6)} - \text{contour}]$$

Overview of theoretical framework: contours

2nd step

New variable:

$$t = c_2 \sqrt{u}$$
, where $c_2 = \sqrt{2F(c_0) / F''(c_0)}$

Using a new variable u one can write the inverse Mellin transform in the form

$$f(x,Q^2) = \frac{c_2}{2\pi} \int_0^\infty \frac{du}{\sqrt{u}} e^{-u} H_1(u),$$

where the function H(u) up to order $O(u^2)$ reads as

$$H_1(u) = \operatorname{Re}\left[e^{u}\left(1 - ic_3c_2\sqrt{u} - 4ic_6c_2^3 u^{3/2}\right)F\left(z(c_2\sqrt{u}), Q^2\right)\right]$$

To the contour $C_K^{(6)}$ corresponds

$$z(u) = c_0 + ic_2 \sqrt{u} + \frac{c_3}{2} c_2^2 u + c_6 c_2^4 u^2$$

$$c_3 = \frac{F^{(3)}(c_0)}{3F''(c_0)}, \ c_4 = \frac{c_3 F^{(4)}(c_0)}{12F''(c_0)}, \ c_5 = \frac{F^{(5)}(c_0)}{120F''(c_0)}, \ \text{and} \ c_6 = \left(c_4 - c_5 - \frac{3}{8}c_3^3\right).$$

Overview of theoretical framework: contours

For the evaluating the integtal the generalized Gauss – Laguerre quadrature formula is used

$$\int_{0}^{\infty} \frac{du}{\sqrt{u}} e^{-u} H_{1}(u) \cong \sum_{j=1}^{n} w_{j} H_{1}(u_{j}),$$
(2)

where the u_i are the zeros of the generalized Gauss – Laguerre polynomials $L_n^{(-1/2)}(u)$.

This was the key achievement of the method proposed by Kosower. We'll see later that the one point (n=1) quadrature formula (2) gives an accuracy of about a few percent.

[Table for $xF_3(x,Q_0^2)$]

Comparison of contours



 \checkmark the main contribution to the integral (1a) comes from the region near the saddle point, where the curves practically coincide

 \checkmark the difference in the behavior of contours is more pronounced for small values of Bjorken-x variable

Relative accuracy

$$\varepsilon(n) = \frac{f_n(x, Q^2) - f^{exact}(x, Q^2)}{f^{exact}(x, Q^2)}, \text{ where } f_n = \sum_{j=1}^n w_j H_1(u_j), f^{exact} = xF_3(x, Q_0^2).$$

Table for $xF_3(x,Q_0^2)$: $C_K^{(3)}$ -contour

x	$xF_3^{exact}(x)$	n = 1	n=2	n = 4	n = 6	n = 8	n = 10
0.001	0.0430001482	0.030	$0.19 \cdot 10^{-2}$	$0.26 \cdot 10^{-4}$	$-0.16 \cdot 10^{-5}$	$-8.20 \cdot 10^{-8}$	$-5.3 \cdot 10^{-8}$
0.01	0.1890698425	0.025	$0.18\cdot 10^{-2}$	$-0.66 \cdot 10^{-4}$	$-0.25 \cdot 10^{-4}$	$0.36 \cdot 10^{-5}$	$-3.7 \cdot 10^{-8}$
0.1	0.7365980291	-0.0034	$0.84 \cdot 10^{-3}$	$0.65 \cdot 10^{-5}$	$-0.31 \cdot 10^{-5}$	$-5.97 \cdot 10^{-7}$	$-7.1 \cdot 10^{-8}$
0.2	0.9151997245	-0.0043	$0.73 \cdot 10^{-3}$	$0.51 \cdot 10^{-5}$	$-8.12 \cdot 10^{-7}$	$-3.29 \cdot 10^{-8}$	$-7.32 \cdot 10^{-9}$
0.3	0.8636734952	0.0003	$0.11 \cdot 10^{-3}$	$-0.53 \cdot 10^{-5}$	$3.42 \cdot 10^{-7}$	$-2.12 \cdot 10^{-8}$	$2.14 \cdot 10^{-10}$
0.5	0.4625246243	0.0078	$-0.19 \cdot 10^{-3}$	$0.23 \cdot 10^{-5}$	$-6.77 \cdot 10^{-8}$	$1.95 \cdot 10^{-9}$	$2.16 \cdot 10^{-10}$
0.8	0.0306079020	0.012	$-0.46 \cdot 10^{-4}$	$-0.24 \cdot 10^{-5}$	$1.32 \cdot 10^{-7}$	$-1.31 \cdot 10^{-9}$	$-6.53 \cdot 10^{-10}$
0.95	0.0002552325	0.012	$-0.28 \cdot 10^{-4}$	$-0.35 \cdot 10^{-5}$	$0.35 \cdot 10^{-6}$	$-0.30 \cdot 10^{-9}$	$-0.39 \cdot 10^{-9}$

Table for the $xF_3(x,Q_0^2)$: $C_{\kappa}^{(6)}$ -contour

x	n = 1	n=2	n = 4	n = 6	n = 8	n = 10
0.01	0.024	$0.59 \cdot 10^{-2}$	$0.16 \cdot 10^{-3}$	$-0.57 \cdot 10^{-4}$	$0.32 \cdot 10^{-4}$	$-0.16 \cdot 10^{-8}$
0.3	0.0003	$0.91 \cdot 10^{-4}$	$-0.17 \cdot 10^{-5}$	$1.97 \cdot 10^{-7}$	$-1.90 \cdot 10^{-8}$	$-2.55 \cdot 10^{-9}$
0.8	0.012	$-0.41 \cdot 10^{-3}$	$-1.06 \cdot 10^{-7}$	$0.50 \cdot 10^{-7}$	$-1.70 \cdot 10^{-9}$	$3.55 \cdot 10^{-11}$

From Q_0^2 to Q^2

$$Q^{2} \text{-evolution:} \quad M_{3}^{NS}(z,Q^{2}) = M_{3}(z,Q_{0}^{2}) \exp\left\{\ln\left[\frac{\alpha_{s}(Q_{0}^{2})}{\alpha_{s}(Q^{2})}\right]\frac{\gamma_{NS}^{(0)}(z)}{2\beta_{0}}\right\}$$

$$xF_{3}(x,Q^{2}) = \frac{1}{2\pi i} \int_{C} dz \ x^{-z}M_{3}(z,Q^{2})$$

Is it possible to use contour $C_K(Q_0^2)$ for calculation of structure functions at $Q^2 \neq Q_0^2$?



Table. The number of polynomials which is needed for achieving $\mathcal{E}(n)$ better than 10^{-4} and 10^{-5} for $xF_3(x, Q^2 = 100 \text{ GeV}^2)$ for two types of contour of integration.

	$\varepsilon = 10^{-4}$	$\varepsilon = 10^{-4}$	$\varepsilon = 10^{-5}$	$\varepsilon = 10^{-5}$
x	$C_K(x,Q^2)$	$C_K(x,Q_0^2)$	$C_K(x,Q^2)$	$C_K(x,Q_0^2)$
0.001	4	5	7	8
0.01	3	4	5	7
0.1	3	4	5	7
0.5	3	3	4	4
0.8	2	3	4	4

The contour $C_{\mathcal{K}}(x, Q^2)$ works more accurately than the contour $C_{\mathcal{K}}(x, Q_0^2)$, however this advantages are compensated if using the $C_{\mathcal{K}}(x, Q_0^2)$ increase the number of terms in the quadrature formula (2) by 1-2 units.

At large x -values the number of terms in the sum (2) less, than at small x. The contour $C_{\kappa}(x, Q_0^2)$ can be considered as universal, i.e. applicable for any value of Q^2 . The similar result was obtained for other cases: $x\Delta q_3$, $x\Delta q_8$, $D_{u_v}^{\pi^+}$.

Other example for the Kosower contour



No accounting of asymptotic behavior of a contour of a constant phase.

Basic feature of a new approach: simple example

$$F(\mathbf{x}) = \mathbf{x}^{a} \qquad \mathbf{x} \in [0,1]$$

Mellin's moments $M(z) = \int_{0}^{1} d\mathbf{x} \ \mathbf{x}^{n-1} F(\mathbf{x}) = \frac{1}{z+a} = \frac{\Gamma(\alpha+z)}{\Gamma(\alpha+1+z)}$
$$F(\mathbf{x}) = \frac{1}{2\pi i} \int_{C} dz \ \mathbf{x}^{-z} M(z) = \frac{1}{2\pi i} \int_{\delta-i\infty}^{\delta+i\infty} dz \frac{e^{uz}}{z+a}, \quad u \equiv -\ln(\mathbf{x})$$

C usually runs parallel to the imaginary axis and lies to the right of the rightmost pole and $\delta > -a$.

$$\Phi(z) \equiv \frac{e^{uz}}{z+a} \qquad z(y) = x(y) + iy$$

Selecting the imaginary part of Φ and imposing the condition on the contour $\text{Im}[\Phi(z)] = 0$, we find the equation for the contour of the stationary phase C_{st} : $[2x(y)-1]\sin(uy) - 2y\cos(uy) = 0$.

The solution of this equation which provides continuity of the contour at y = 0 has the form

$$\begin{bmatrix} x_{st}(y) = -a + y \operatorname{ctg}(uy), \ y \neq 0 \\ \lim_{y \to 0} x_{st}(y) = -a + \frac{1}{u} \equiv c_0, \ y = 0 \\ \text{For } \operatorname{Re}|z| \to \infty \quad x_{as}(y) = y \operatorname{ctg}(uy) \quad y_{as} = \frac{\pi}{u} \operatorname{sign}(y) \end{bmatrix}$$

Asymptotics of the contour C_{st} is bounded and is parallel to the real x-axis

To calculate the integral numerically, we apply the Gauss-Legendre quadrature formula

$$\int_{0}^{|y_{as}|} dy H_{2}(y) = \frac{|y_{as}|}{2} \sum_{j=1}^{N} w_{j} H_{2}(y_{j})$$

$$H_{2}(y) = \operatorname{Re}\left[\Phi(n_{as}(y))\left(1 - i\frac{dx_{as}(y)}{dy}\right)\right] / \pi \quad (3)$$

$$y_{j} = \frac{|y_{as}|}{2}(x_{j} + 1), \quad x_{j} - \operatorname{roots}$$

$$w_{j} = \frac{2}{(1 - x_{j}^{2})[P_{n}(x_{j})]^{2}} - \operatorname{weight coefficients}$$

The asymptotics of the contour of the stationary phase can be found without solving above equation, but only considering the asymptotics of the integrand $\Phi(z) \sim \frac{e^{uz}}{z}.$

Calculating the argument of Φ and equating its imaginary part to zero

for Re
$$|z| \rightarrow \infty$$
 $uy - \arctan \frac{y}{x(y)} = \pi$
Im $z \stackrel{6}{=} \frac{|y_{as}|}{|y_{as}|} \stackrel{(y_{as})}{=} \frac{-iy_{as}}{|u|} \stackrel{(y_{as})}{=}$

Example of two saddle points

$$F(\mathbf{x}) = \mathbf{x}^{a}(1 - \mathbf{x}) \qquad 0 < \mathbf{x} < 1$$

Mellin's moments $M(z) = \int_{0}^{1} d\mathbf{x} \ \mathbf{x}^{n-1} F(\mathbf{x}) = \frac{1}{(a+z)(a+1+z)} = \frac{\Gamma(a+z)}{\Gamma(a+2+z)}$
$$F(\mathbf{x}) = \frac{1}{2\pi i} \int_{\delta - i\infty}^{\delta + i\infty} dz \ \frac{e^{uz}}{(a+z)(a+1+z)}, \qquad u \equiv -\ln(\mathbf{x})$$

$$\Phi(z) \equiv \frac{e^{uz}}{(a+z)(a+1+z)} \qquad z(y) = x(y) + iy$$

Selecting the imaginary part of Φ and imposing the condition on the contour

$$\operatorname{Im}\!\left[\Phi(z)\right]\!=\!0,$$

we find the equation for the contour of the stationary phase C_{st}

$$4\sin(uy)x^{2}(y) - 8y\cos(uy)x(y) - (1 + 4y^{2})\sin(uy) = 0$$

$$x^{(1)}(y) = -a - \frac{1}{2} + yctg(uy) + \frac{\sqrt{\sin(uy)^2 + 4y^2}}{2\sin(uy)} \operatorname{sign}(y)$$

$$c_0^{(1)} = -a - \frac{1}{2} + \frac{1}{u} + \frac{\sqrt{4 + u^2}}{2u}$$

$$x_{as}^{(1)}(y) = y \ ctg\left(\frac{uy}{2}\right) \qquad y_{as} = \frac{2\pi}{u} \operatorname{sign}(y)$$

$$x^{(2)}(y) = -a - \frac{1}{2} + yctg(uy) - \frac{\sqrt{\sin(uy)^2 + 4y^2}}{2\sin(uy)} \operatorname{sign}(y)$$

$$c_0^{(2)} = -a - \frac{1}{2} + \frac{1}{u} - \frac{\sqrt{4 + u^2}}{2u}$$

$$x_{as}^{(2)}(y) = -y \ tg\left(\frac{uy}{2}\right) \qquad y_{as} = \frac{\pi}{u} \operatorname{sign}(y)$$

$$y = \frac{2}{u} \ W_t\left(\frac{u}{2}x\right) \qquad [Markushin, Rosenfelder, Schreiber, Nov. Cim. B 117 (2002)]$$



$$\Phi(z) \sim \frac{e^{uz}}{z^2}$$

$$\operatorname{Re} |z| \to \infty$$

$$z_{as}^{(1)} = y \operatorname{ctg}\left(\frac{uy}{2}\right) + c_0^{(1)} - \frac{2}{u} + iy$$

$$z_{as}^{(2)} = -y \operatorname{tg}\left(\frac{uy}{2}\right) + c_0^{(2)} + iy$$

The asymptotic contours after shifting practically merge with the corresponding exact contours.

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New contour for structure function

$$\Phi^{\text{DIS}}(z) \sim e^{\omega_B z} A \Gamma(\beta + 1) \frac{1 + \gamma}{z^{\beta + 1}}, \qquad \omega_B \equiv -\ln(x_B)$$

Calculating the argument of the Φ – function and equating its imaginary part to zero, we arrive at the equation $\omega_B y - (\beta + 1) \arg z = 0$. From this equation it follows that as z tends to -infinity, the argument z tends to $\pm \pi$, and we get the asymptotic behavior

$$x_{as}^{\text{DIS}}(y) = y \operatorname{ctg}\left(\frac{\omega_B y}{\beta+1}\right), \quad y_{as}^{\text{DIS}} = \frac{(\beta+1)\pi}{\omega_B}\operatorname{sign}(y)$$

The asymptotics of the stationary phase contour are parallel to the real axis.

$$z_{as}^{\text{DIS}} = y \operatorname{ctg}\left(\frac{\omega_B y}{\beta + 1}\right) + c_0 - \frac{\beta + 1}{\omega_B} + iy$$



The contour C_{as} works more accurately than the contour C_{k} for N>30.



$$x(y,Q^2) = \operatorname{yctg}\left[\frac{\omega_B y}{(\beta+1) + \Delta(Q^2)}\right] \qquad \qquad \Delta(Q^2) \equiv \frac{16}{33 - 2n_f} \ln\left[\frac{\alpha_s^{LO}(Q_0^2)}{\alpha_s^{LO}(Q^2)}\right]$$

$$y(x,Q^{2}) = \pm \frac{\left[(\beta+1) + \Delta(Q^{2}) \right]}{\omega_{B}} W_{ct} \left(\frac{\omega_{B} x}{(\beta+1) + \Delta(Q^{2})} \right) \qquad \omega_{B} \equiv -\ln(x_{B})$$

$$y_{as}^{DIS}(Q^2) = \pm \frac{\left[(\beta + 1) + \Delta(Q^2) \right] \pi}{\omega_B}$$

The contour $C_{as}(Q^2)$ in higher orders of the perturbation theory QCD will coincides with the LO expression with the replacement only of $\alpha_s^{LO}(Q^2)$ by an expression for running coupling in the corresponding order of the perturbation theory.

Example I: MB integral arising in Feynman diagrams

$$I_{I}(s) = \frac{1}{2\pi i} \int_{\delta - i\infty}^{\delta + i\infty} dz \, (-s)^{-z} \, \frac{\Gamma^{3}(-z)\Gamma(1+z)}{\Gamma(-2z)\Gamma(1-z)\Gamma(2+z)} \qquad (-s \Longrightarrow x_{B})$$

In the region 0 < -s < 4 $I_I(s) = -s$

for
$$-s > 4$$
 $I_I(s) = 2\ln(-s) - s\left(1 - \sqrt{1 + \frac{4}{s}}\right) + 4\ln\left[\frac{1}{2} + \frac{1}{2}\sqrt{1 + \frac{4}{s}}\right]$

Asymptotic stationary phase integration contour

$$z_{as}(y) = x_{as}(y) + iy$$

$$x_{as}(y) = y \operatorname{ctg} \left\{ \frac{2}{5} \left[-\ln(-s) + \ln 4 \right] \cdot y + \frac{3}{2} \pi \operatorname{sign}(y) \right\}, \quad \operatorname{Re} |z| \to \infty$$

$$y_{as} = \pm \frac{\pi}{-\ln(-s) + \ln 4} \qquad 0 < -s < 4$$

$$y_{as} = \pm \frac{3}{2} \frac{\pi}{|-\ln(-s) + \ln 4|} \qquad -s > 4$$



The proposed contour C_{as} , whose a construction is quite simple, reproduces the behavior of the exact contour C_{st} well, and the use of this contour can provide the required high relative accuracy.

	<i>-s</i> =	= 1/20	-s = 2.0		
N	C_K	C_{as}	C_K	C_{as}	
16	1.2×10^{-8}	1.3×10^{-7}	1.2×10^{-6}	6.5×10^{-5}	
20	6.7×10^{-10}	8.5×10^{-12}	4.0×10^{-6}	3.9×10^{-6}	
30	1.2×10^{-11}	5.7×10^{-14}	5.1×10^{-7}	1.2×10^{-8}	
35	5.8×10^{-13}	5.7×10^{-16}	1.4×10^{-7}	5.8×10^{-11}	

Example II

$$I_{II}(s) = \frac{1}{2\pi i} \int_{\delta - i\infty}^{\delta + i\infty} dz \ (-s)^{z} \ \frac{\Gamma^{4}(-z)\Gamma(1+2z)}{\Gamma^{2}(-2z)\Gamma^{2}(1+z)}$$

In the region $0 < -s < 4^{3}$ $I_{II}(s) = \frac{2}{\pi} \sqrt{-s} \cdot \left[K \left(\frac{1}{2} \cdot \left(1 - \sqrt{1 + \frac{s}{64}} \right) \right) \right]$

K- the complete elliptic integral of the first kind

$$-s > 4^{3} I_{II}(s) = 4 \ln(-s) - 4 \cdot \sum_{n=1}^{\infty} \frac{(2n)!^{3} \cdot (-s)^{-n} \left[6\Psi(2n+1) - 6\Psi(n+1) - 7\ln(-s) \right]}{n!^{6}}$$

The asymptotic behavior of the integrand:
$$\Psi(z) = \frac{d}{dz} \ln \Gamma(z)$$

The asymptotic behavior of the integrand:

$$\Phi(z) \sim \exp\left[uz - \ln(-z) + \left(6z - \frac{3}{2}\right)\ln(2) - \frac{1}{2}\ln z\right], \quad Re \mid z \mid \to \infty$$

$$uy - \frac{3}{2}\arg(z) \pm \frac{4}{\pi}\operatorname{sign}(y) + 3y\ln 4 = 0$$

$$\downarrow$$

$$x_{as}(y) = \operatorname{yctg}\left[\frac{2}{3}(\omega + 3\ln 4)y + \operatorname{sign}(y)\pi\right]$$

The case of a complicated shape of the stationary phase contour



The use of the asymptotic contour of the stationary phase proves to be effective even in this complicated case.



N	- s :	= 20	-s = 128		
	Cas	<i>C</i> _{<i>K</i>}	Cas	Cĸ	
10	1.5 x 10 ⁻³	2.1 x 10 ⁻³	-8.3 x 10 ⁻³	1.1 x 10 ⁻²	
12	-6.8 x 10 ⁻⁴	1.4 x 10 ⁻³	-1.1×10^{-2}	3.9 x 10 ⁻²	
16	-8.5 x 10 ⁻⁷	5.3 x 10 ⁻⁴	2 x 10 ⁻³	8.8 x 10 ⁻²	
20	-3.4 x 10 ⁻⁶	1.9 x 10 ⁻⁴	-2 x 10 ⁻⁴	0.1	
30	1.3 x 10 ⁻⁶	1.5 x 10 ⁻⁵	-4.4 x 10 ⁻⁶	0.22	
35	-3.6 x 10 ⁻⁷	4.2 x 10 ⁻⁶	6.3 x 10 ⁻⁷	0.26	

Conclusions

We proposed the method for constructing an effective contour to calculate with high accuracy one-dimension Mellin-Barnes integrals. This contour is the approximation of the stationary phase contour in the case of their finite asymptotic behavior.

The construction of contour C_{as} is much easier because it is not requires computation of higher derivatives. This gives the advantage for the contour C_{as} at intensive computations related to fitting of experimental data.

It was compared the efficiency of application of the asymptotic stationary phase contour C_{as} and the contour C_{k} . The contour C_{k} turned out to be more effective for a small number of N terms in the Gauss-Laguerre quadrature formula, when the nodes of the quadrature formulas are located near the saddle point. The advantage of the contour C_{as} is manifested at large values of N. The 'regime change' occurs at N~20 for structure function.

It was shown that the contour C_{as} makes it possible to calculate the MB integrals effectively even in the case of a complicated shape of the stationary phase contour.

